An Hamiltonian Approach To State Constrained Optimal Control Problems

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We establish sufficient optimality conditions for strong-local optimality of Pontryagin extremals for some single-input control-affine problems. More precisely, we consider the control problem

$$\dot{\xi}(t) = f_0(\xi(t)) + u(t)f_1(\xi(t)) \quad \text{a.e. } t \in [0, T],
\xi(0) = x_0, \quad \xi(T) \in \mathcal{N}_f,
c(\xi(t)) \le 0 \quad \forall t \in [0, T], \qquad |u(t)| \le 1 \quad \text{a.e. } t \in [0, T],$$

where the state space is a smooth manifold M, the function $c: M \to \mathbb{R}$ defining the state constraint is assumed to be smooth on a neighborhood of its zero-level set; f_0, f_1 are smooth vector fields on M and \mathcal{N}_f is a submanifold of M. We associate with the problem above a cost J to be minimized, that can be either in Mayer form or the minimum time to reach \mathcal{N}_f , i.e. we deal with both the following problems

> minimize $\psi(\xi(T))$, T > 0 fixed, minimize T, T > 0 free.

We study extremals containing a bang arc, a boundary arc, followed by a finite number of bang arcs. The sufficient conditions are given by some regularity conditions on the boundary arc, together with a strengthened version of the necessary conditions, and the coerciveness of a suitable finitedimensional quadratic form. The sufficiency of the provided conditions is proven via Hamiltonian methods. We are currently studying the case when also an internal singular arc is present.

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